

Declarative Machine Learning for Energy Efficient Compiler Optimizations

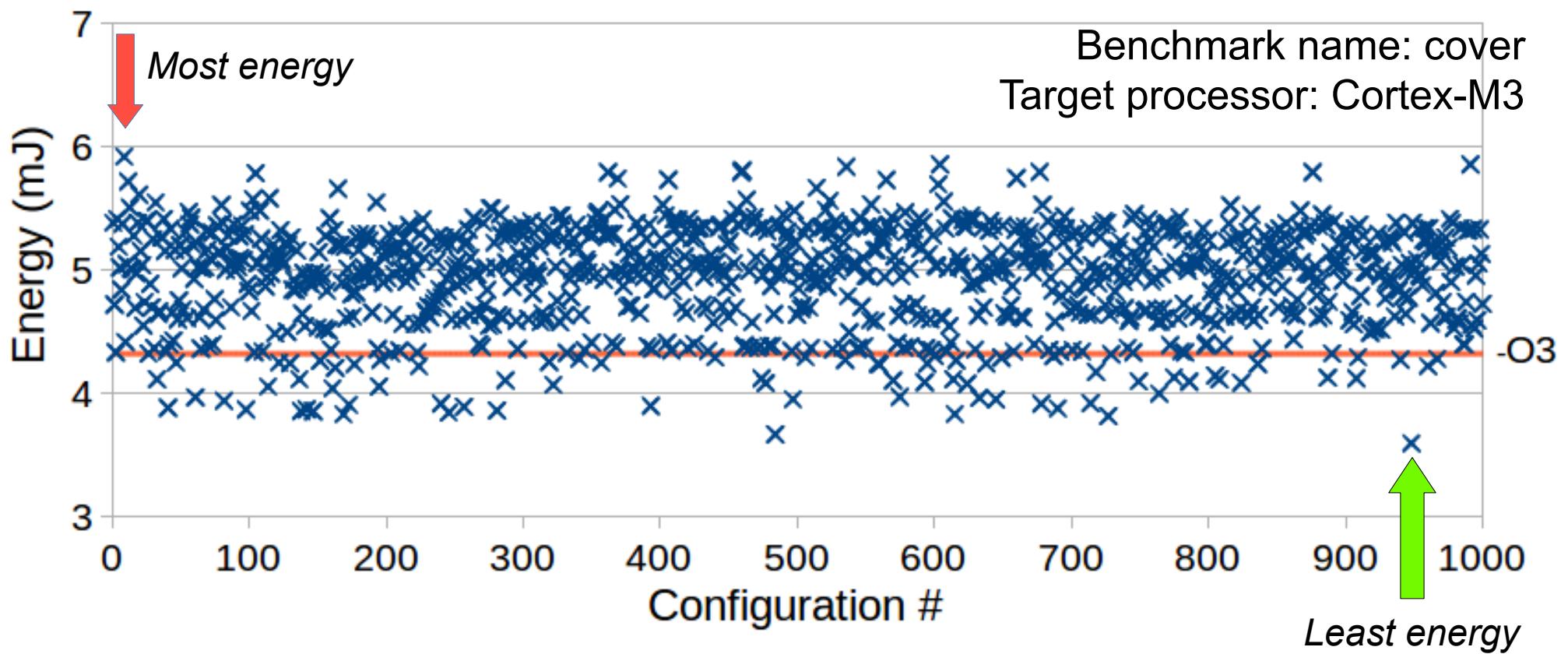
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1000 Random Configurations

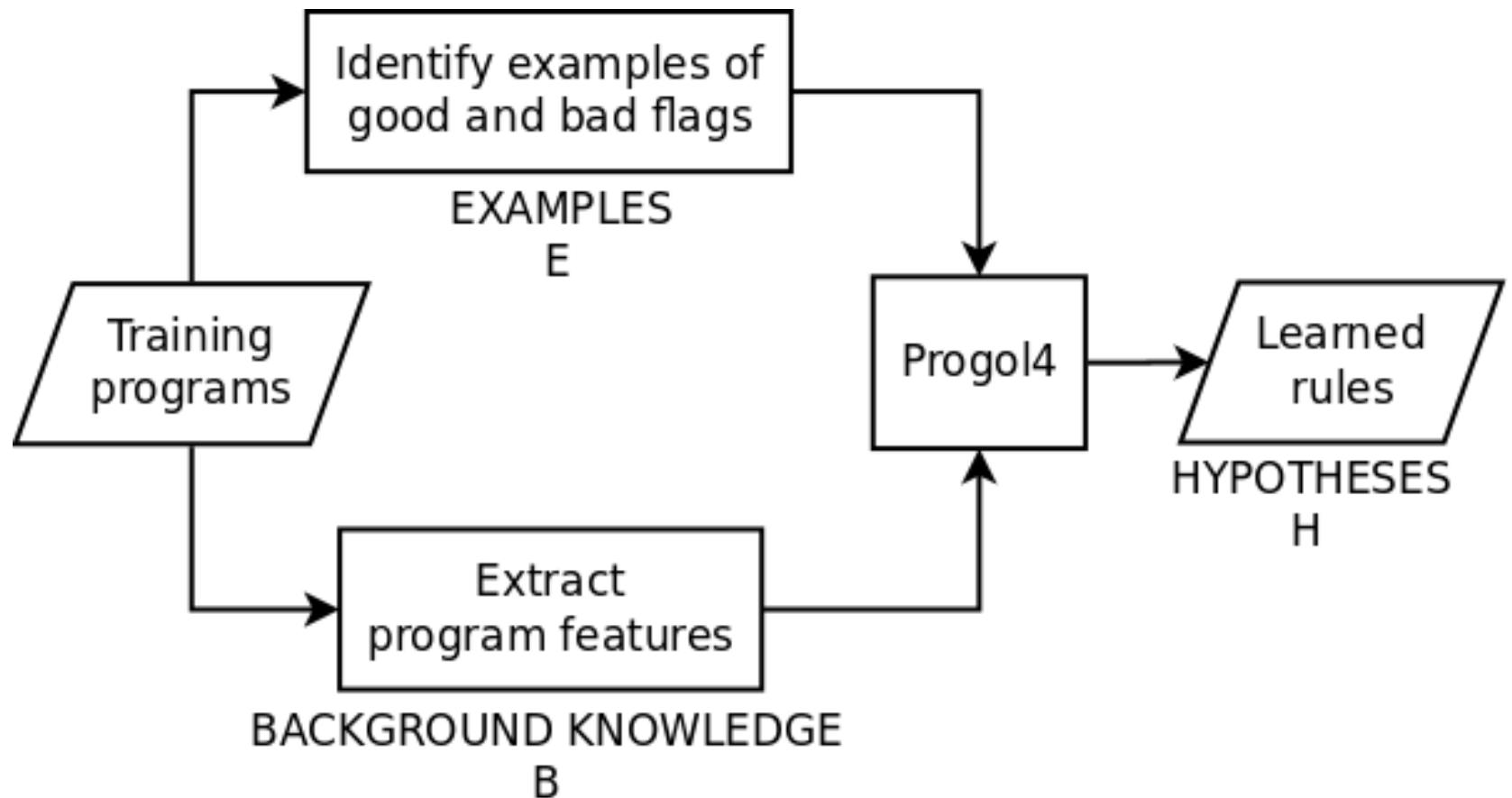


- ✗ Exhaustive search infeasible
- ✗ Random sampling (iterative compilation) slow
- ✓ Predictive approaches

Inductive Logic Programming

- **Declarative inductive learning method**
- Requires:
 - Factual examples E represented as components together with their relationships, and
 - Background knowledge B describing these relations.
- Finds a single (or multiple) hypothesis H
 - expressed in terms of the relations given in B
 - such that every positive and (ideally)
 - no negative example in E is covered by H .

ILP for MAGEEC



Specific examples



General Rules

Identifying Good/Bad Flags

1000 random configurations for each benchmark

Good flag = appears frequently in top configurations

Bad flag = not a good flag ☺

Examples E for Progol:

goodFlag(program1, -finline-functions).

Positive Example

:- badFlag(program1, -finline-functions).

Negative Example

Feature Extraction

Prolog queries regarding the program features + utility functions:

Ft1 - Number of basic blocks

```
featlstn.P : ft(ft1,N) :- findall(B,bb_p(B),L), count_lst(L,N).
```

Ft5 - Number of basic blocks with a single predecessor

```
featlstn.P :
```

```
    edge_dest_pr2(B,N) :- bb_p(B), findall(E,edge_dest(E,B),L),  
    count_lst(L,N).
```

```
    edge_dest_pr2_sel1(B) :- edge_dest_pr2(B,N), N = 1.
```

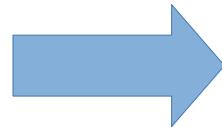
```
ft(ft5,N) :- findall(B,edge_dest_pr2_sel1(B),L), count_lst(L,N).
```

Feature Extraction

- Ft15 - Number of basic blocks with number of instructions greater than 500
 - **featlstn.P** :
 - `bb_stmt_in(B,ST) :- bb_stmt_f(B,ST).`
 - `bb_stmt_in(B,ST) :- bb_stmt_n(B,_,ST).`
 - `bb_stmt_in_pr1(B,N) :- bb_p(B), findall(ST,bb_stmt_in(B,ST),L), count_lst(L,N).`
 - `bb_stmt_in_pr1_sel3(B) :- bb_stmt_in_pr1(B,N), N > 500.`
 - `ft(ft15,N) :- findall(B,bb_stmt_in_pr1_sel3(B),L), count_lst(L,N).`

Background Knowledge

Feature 1 = 0.5



ft(ft1, program1, 0.5).

Feature 2 = 0.7

ft(ft2, program1, 0.7).

Feature 3 = 0.32

ft(ft3, program1, 0.32).

...

...

Background relations:

quartile(P,Ft,1) :- ft(Ft,P,N), qt1(Ft,Q1), N=<Q1.

quartile(P,Ft,2) :- ft(Ft,P,N), qt1(Ft,Q1), qt2(Ft,Q2), N>Q1, N=<Q2.

quartile(P,Ft,3) :- ft(Ft,P,N), qt2(Ft,Q2), qt3(Ft,Q3), N>Q2, N=<Q3.

quartile(P,Ft,4) :- ft(Ft,P,N), qt3(Ft,Q3), N>Q3.

Background Knowledge

Feature 1 = 0.5



ft(ft1, program1, 0.5).

Feature 2 = 0.7

ft(ft2, program1, 0.7).

Feature 3 = 0.32

ft(ft3, program1, 0.32).

...

...

Background relations:

quartile(P,Ft,1) :- ft(Ft,P,N), qt1(Ft,Q1), N=<Q1.

quartile(P,Ft,2) :- ft(Ft,P,N), qt1(Ft,Q1), qt2(Ft,Q2), N>Q1, N=<Q2.

quartile(P,Ft,3) :- ft(Ft,P,N), qt2(Ft,Q2), qt3(Ft,Q3), N>Q2, N=<Q3.

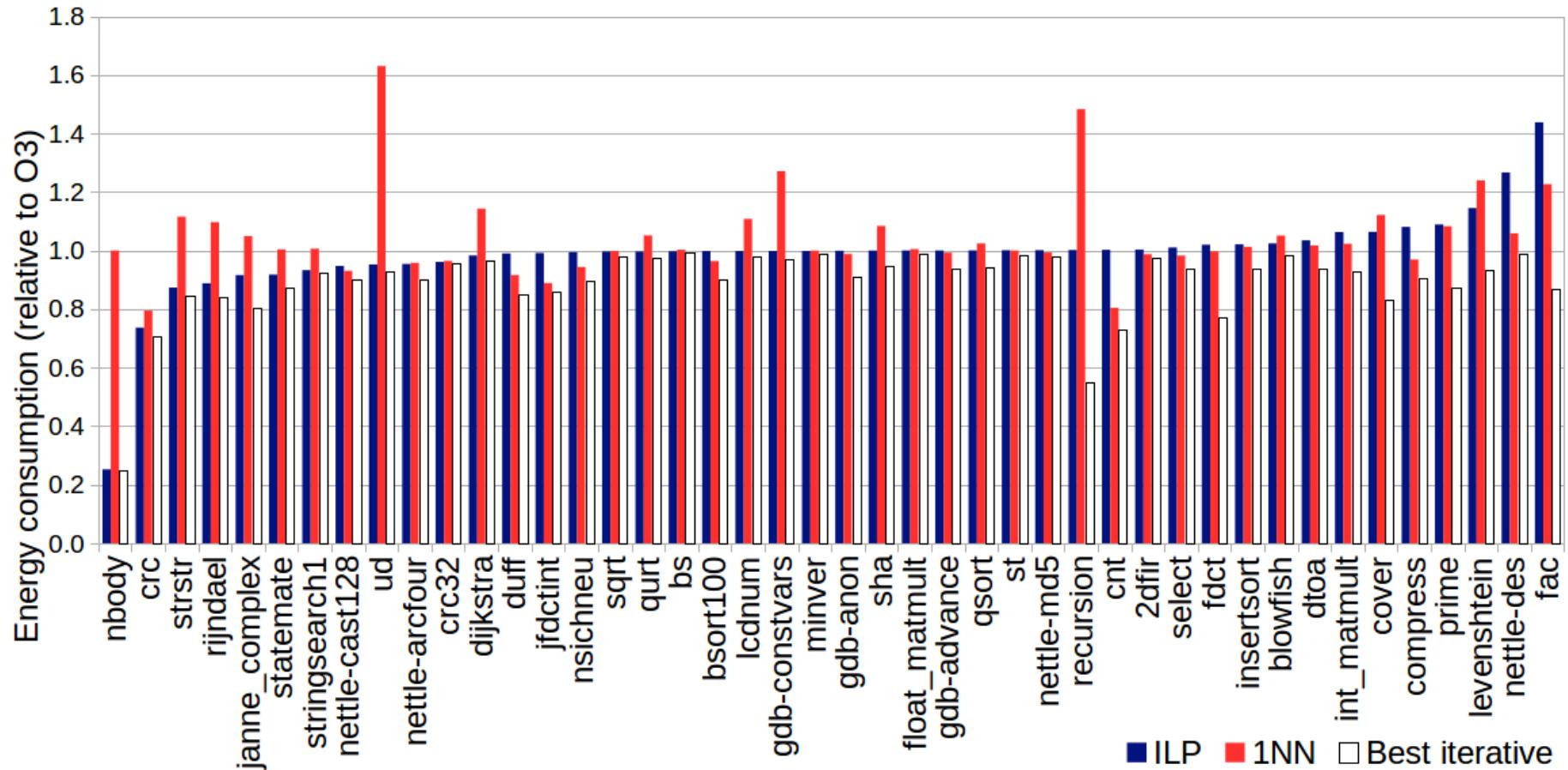
quartile(P,Ft,4) :- ft(Ft,P,N), qt3(Ft,Q3), N>Q3.

Learning Results

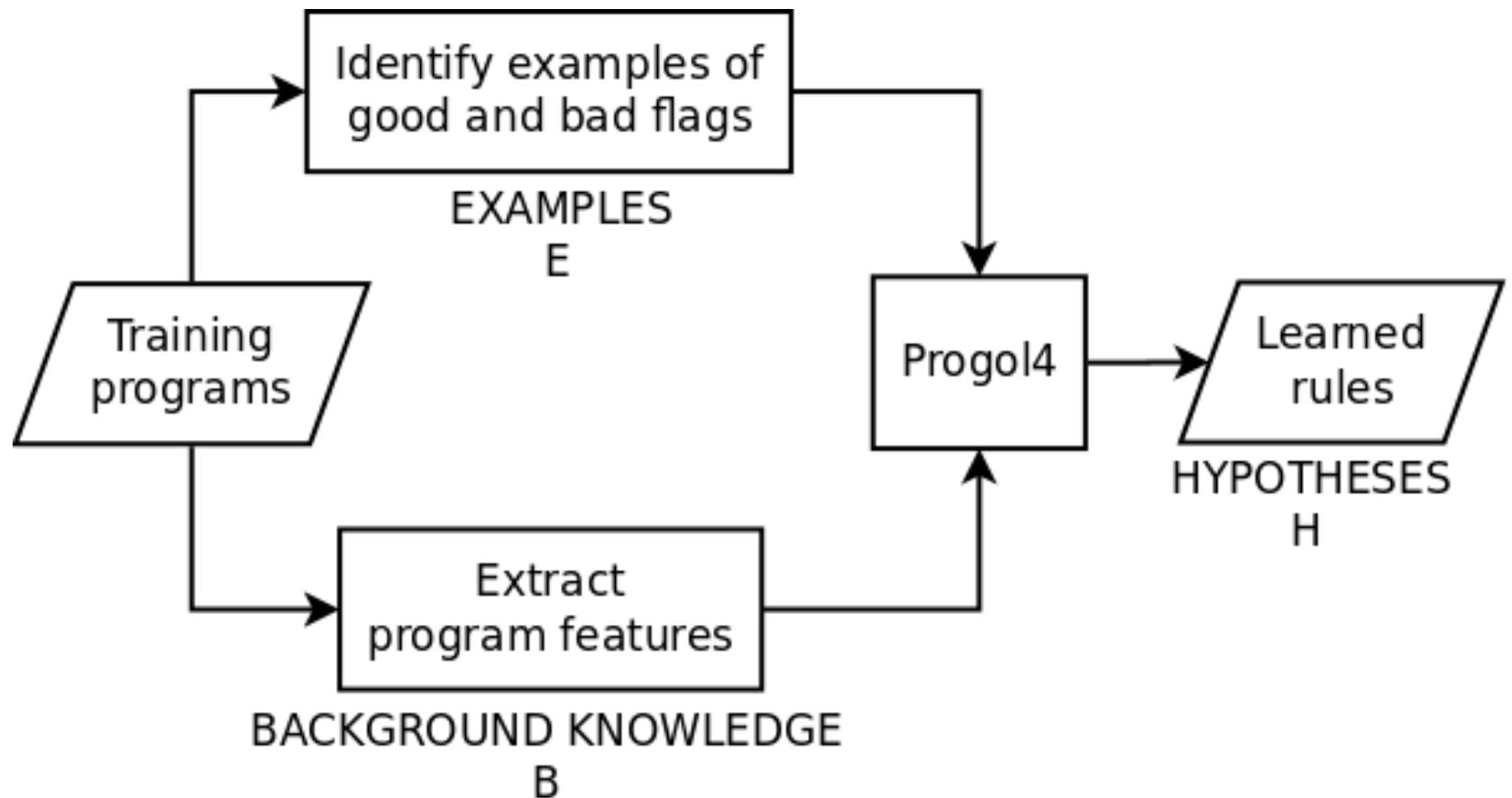
goodFlag(A,-finline-small-functions).

badFlag(A,-fsection-anchors) :- quartile(A,ft22,3).

Preliminary Results: Leave-One-Out Cross Validation



ILP for MAGEEC

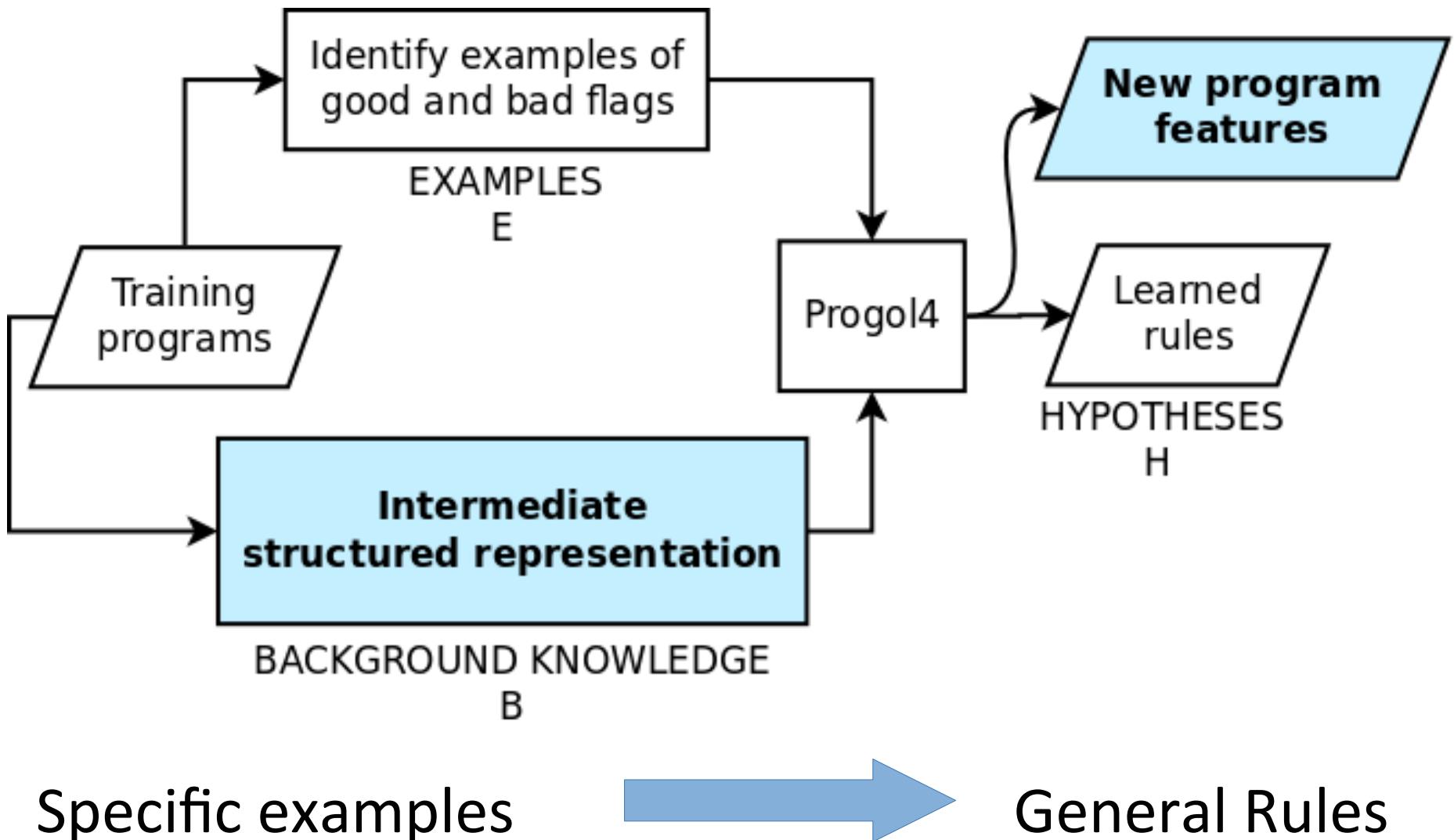


Specific examples



General Rules

Future Work



Questions?

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