

# Imperfection-Insensitive Continuous Tow-Sheared Cylinders

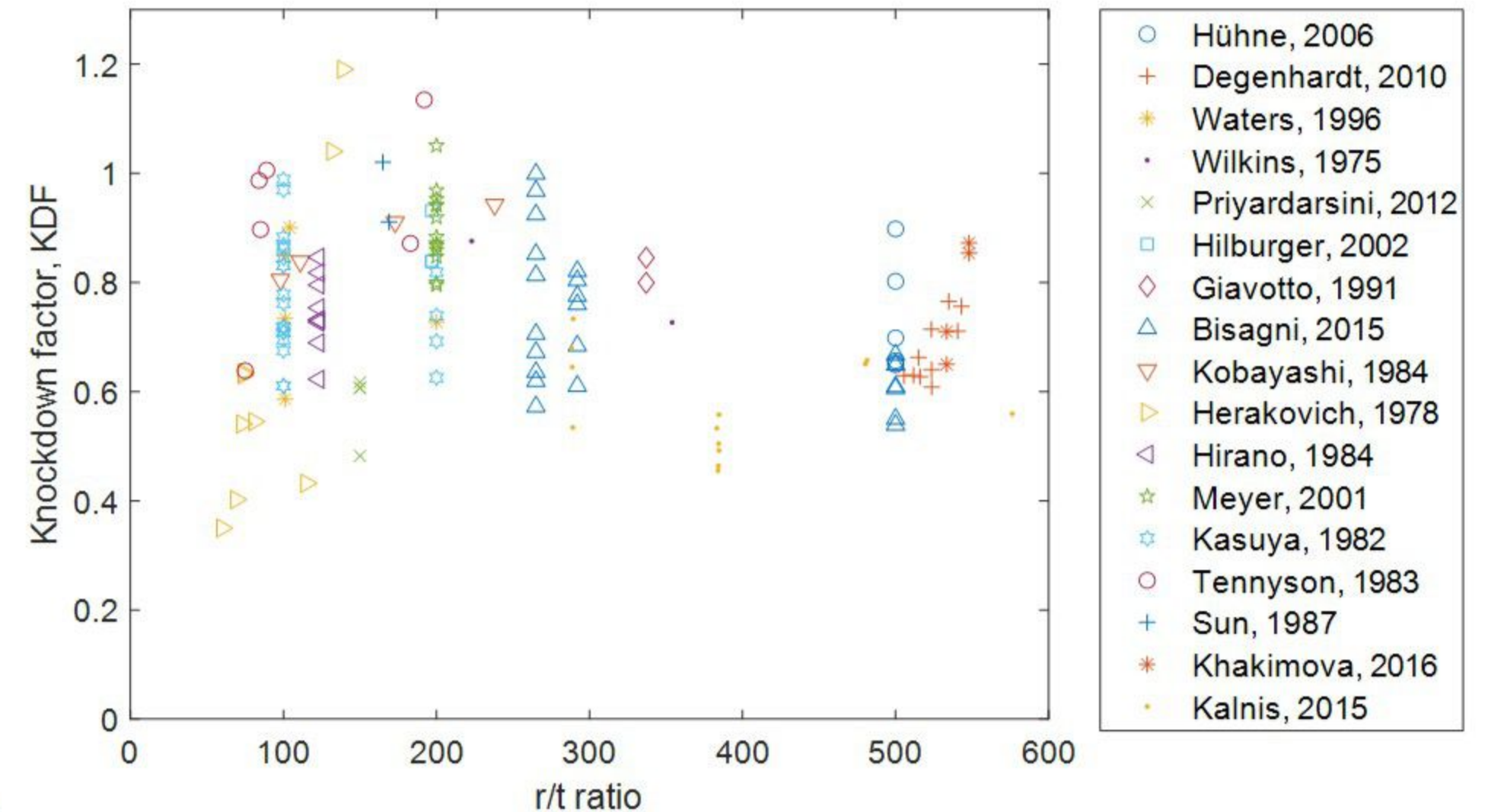
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## Problem

$$KDF = \left( \frac{P_{ex}^*}{P_{cr}^*} \right)$$

$$P_{cr}^* = \frac{2\pi Et^2}{\sqrt{3(1-\nu^2)}}$$

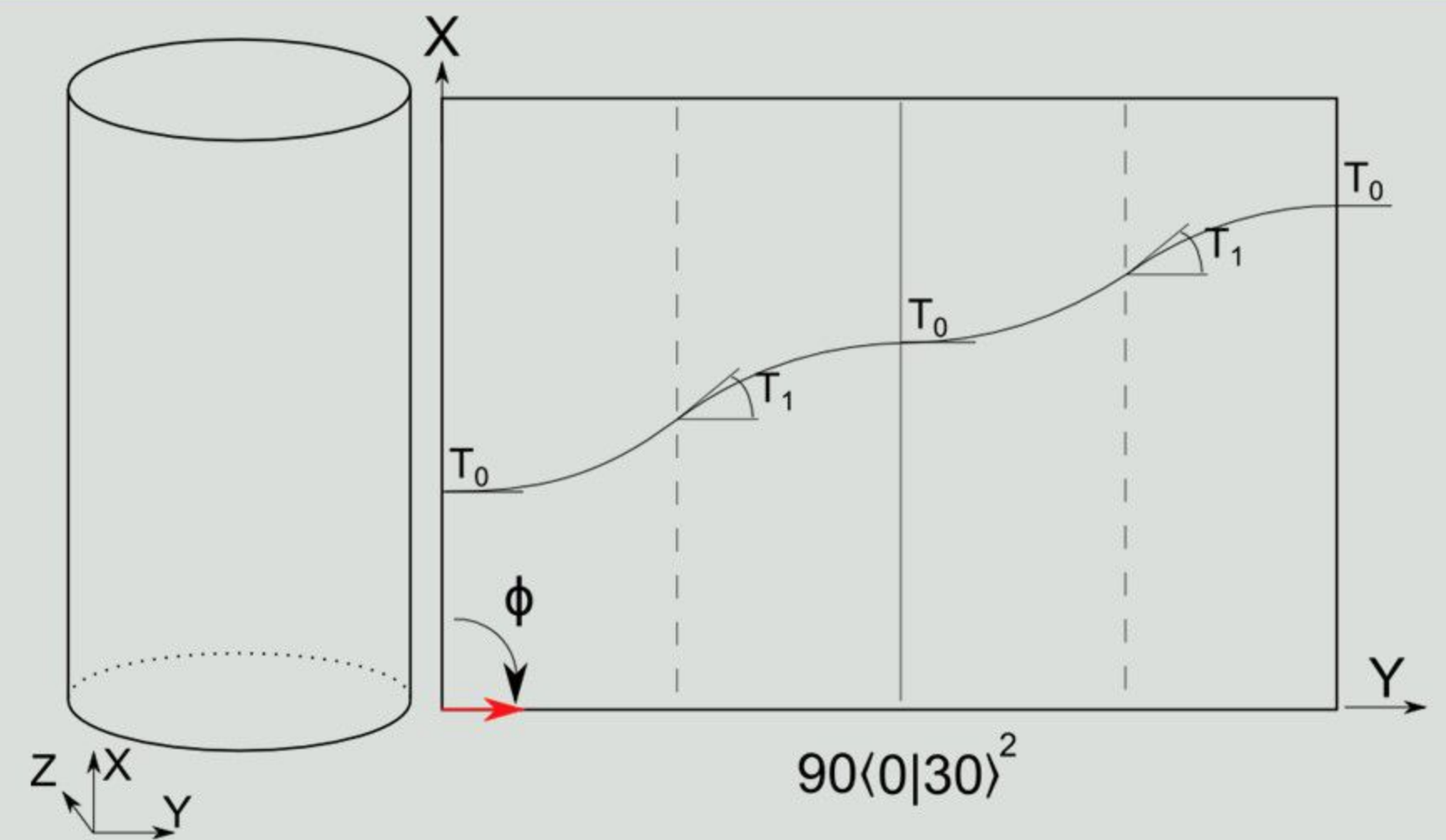
- Discrepancy between theory and experimental results due to imperfection sensitivity
- Conservative design philosophy leading to inefficient, heavy structures



## Nomenclature

$$\phi \langle T_0 | T_1 \rangle^n$$

- $\phi$ : angle from X-axis to define cross-head direction
- $T_0$ : angle from  $\phi$  that defines initial shearing angle
- $T_1$ : angle from  $T_0$  that defines final shearing angle
- $n$ : periodicity, i.e. how many the cycle  $T_0 \rightarrow T_1 \rightarrow T_0$  happens

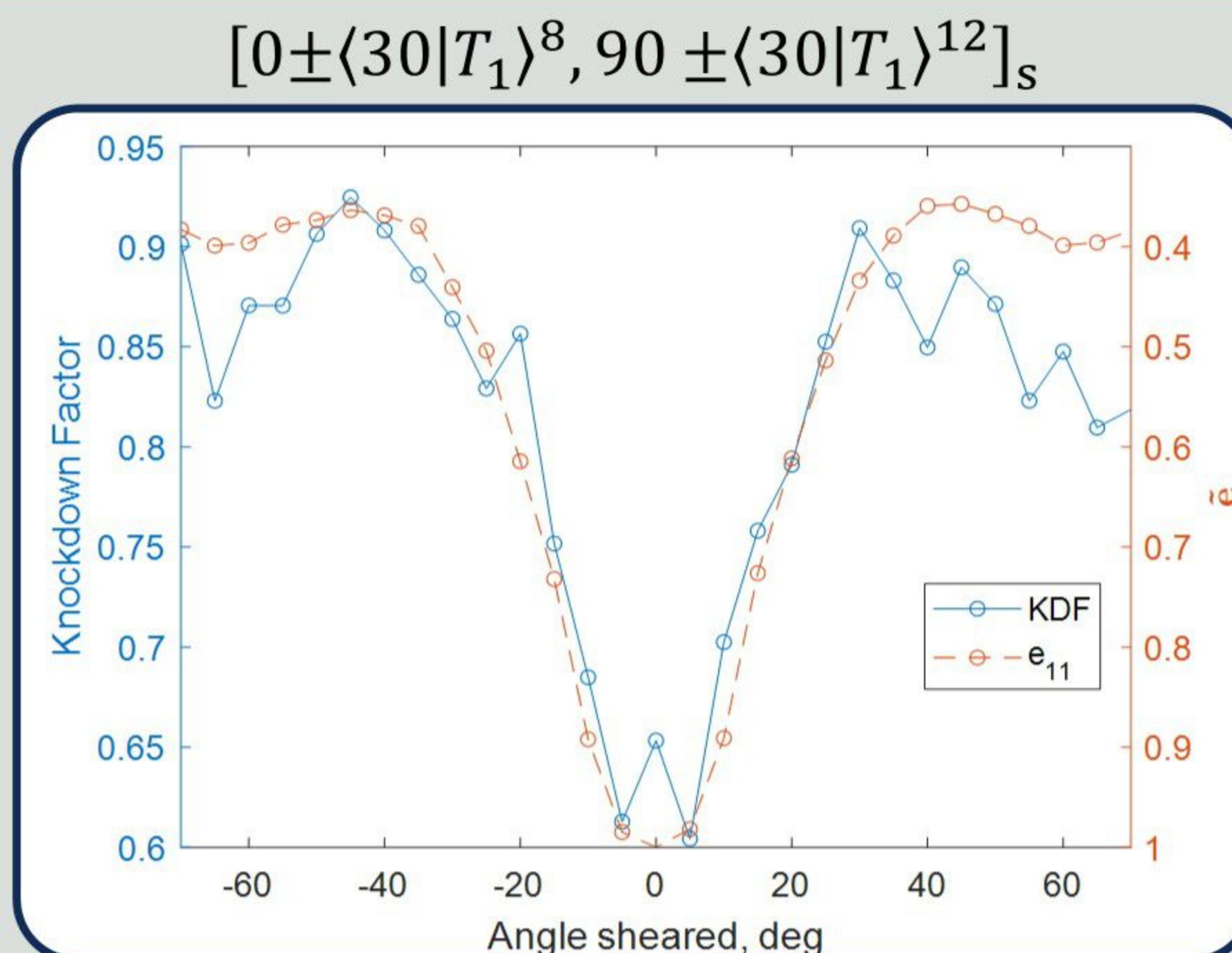


## Results

$$KDF = \left( \frac{P_\lambda}{P_{cr}} \right)$$

$$P = P_\lambda \quad P = P_{cr}$$

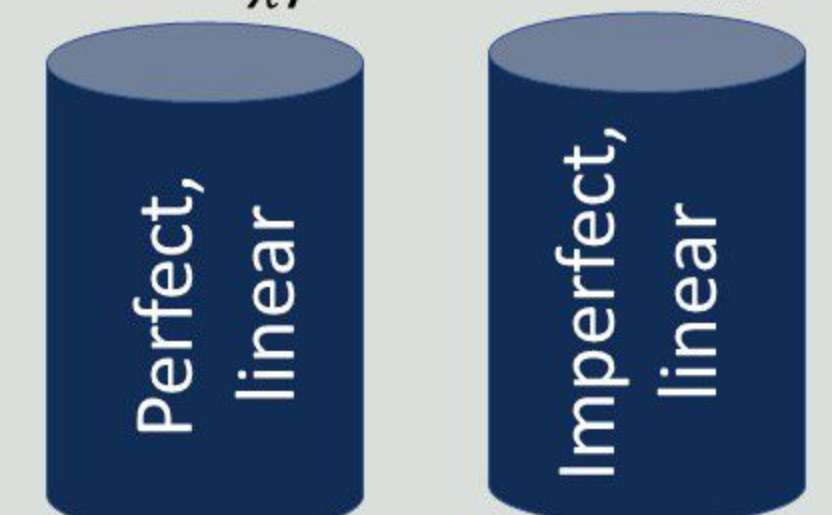
$$u = u_\lambda \quad u = u_{cr}$$



$$\tilde{e} = \text{rms} (\bar{e}_{11}^{\text{perf}} - \bar{e}_{11}^{\text{imp}})$$

$$P = P_\lambda/2 \quad P = P_{cr}/2$$

$$u = u_\lambda/2 \quad u = u_{cr}/2$$



- Optimisation to maximise imperfect buckling load across a range of imperfections
- Increased** average imperfect buckling load
- Decreased** standard deviation and variance

Cylinder	$P^\mu$ [kN]	$\sigma$ [kN]	Var [N]
$[0 \pm \langle 20   25 \rangle^2, 90 \pm \langle 35   25 \rangle^9]_s$	193.4	4.16	84.7
$[\pm 45, 0, 90]_s$	170.6	5.72	178
$\Delta\%$	<b>+13%</b>	<b>-32%</b>	<b>-71%</b>